

Early Journal Content on JSTOR, Free to Anyone in the World

This article is one of nearly 500,000 scholarly works digitized and made freely available to everyone in the world by JSTOR.

Known as the Early Journal Content, this set of works include research articles, news, letters, and other writings published in more than 200 of the oldest leading academic journals. The works date from the mid-seventeenth to the early twentieth centuries.

We encourage people to read and share the Early Journal Content openly and to tell others that this resource exists. People may post this content online or redistribute in any way for non-commercial purposes.

Read more about Early Journal Content at http://about.jstor.org/participate-jstor/individuals/early-journal-content.

JSTOR is a digital library of academic journals, books, and primary source objects. JSTOR helps people discover, use, and build upon a wide range of content through a powerful research and teaching platform, and preserves this content for future generations. JSTOR is part of ITHAKA, a not-for-profit organization that also includes Ithaka S+R and Portico. For more information about JSTOR, please contact support@jstor.org.

or area the discussion of the limits involved in their evaluation must be post-The treatment of all problems in limits belongs essentially to the differential and integral calculus; and it might be far better to leave these difficult questions until the analytic means for adequately handling them have been developed. We shall, however, sketch in the ideas which come up in the proof that a tangent exists at any point M of a circle. First choose a point P on one side of M and draw the secant MP. Then let P approach M as a limit. It may be shown that as P approaches M, the secant MP turns always in one direction about the point P. This comes of the fact that the circle is a convex curve. But MP does not turn as far as the line formed by producing the radius through P. Hence, analogously to Theorem 4, there exists a limiting direction of the secant We have therefore established the existence of a tangential direction on one side of the point M. By taking the point P on the other side we may likewise establish the existence of a tangential direction on that side. directions may be shown to be opposite directions along the same line through M; and the proof of the existence of a tangent is then complete. With these suggestions we shall leave the problem to the reader.

ON COMPLETE SYMMETRIC FUNCTIONS.*

By DR. E. D. ROE, Jr., Professor of Mathematics in Syracuse University.

PART I. INTRODUCTION.

1. DEFINITIONS, NOTATION, AND OBJECT OF THE PAPER.

Let $\phi(a_1, a_2, \dots, a_n)$ be any rational function of the a's. Let $s = \begin{pmatrix} 1 & 2 & 3 & \dots & n \\ i_1 i_2 i_3 & \dots & i_n \end{pmatrix}$, i_1, i_2, \dots, i_n being some permutation of 1, 2, 3,, n; then s is an operator which converts the index r into i_r ; also s applied to ϕ , converts it into ϕ_i , a function in which the a's have been permuted. This is expressed by writing

$$(1) s\phi = \phi_i.$$

Of such operators s there are n! Applying each one to ϕ , we get ϕ_1 , ϕ_2 ,, $\phi_{n!}$. Let

$$\Phi = \phi_1 + \phi_2 + \dots + \phi_{nl}.$$

Then Φ is a symmetric function of the α 's. In particular cases it may happen that ϕ_1 , ϕ_2 ,, ϕ_{nl} , are not all different, but it can be proved that each dis-

^{*}A paper presented February 1, 1904, before The Mathematical Club of Syracuse University.

tinct ϕ is repeated the same number, r, of times, that the number of distinct ϕ 's is n!/r, and that

(3)
$$\Phi = r(\phi_1 + \phi_2 + \dots + \phi_{n!/r}).$$

We may observe that Φ and a determinant \triangle of the *n*th order are related to each other by means of s. For, by applying the different values of s to the second set of indices of the principal diagonal term $a_{11}a_{22}$ a_{nn} , and also by simultaneously taking account of the number of inversions of order, i, among i_1 , i_2 ,, i_n , we get,

$$(4) \qquad (-1)^{i}s(a_{11}a_{12}....a_{nn}) = (-1)^{i}a_{1i_{1}}a_{2i_{2}}....a_{ni_{n}},$$

that is, we get every term of the determinant in question. Hence in general to every term of \triangle corresponds a term of Φ , and conversely, while in particular cases [as in (3)] to r terms of \triangle may correspond the same term of Φ .

We limit the present discussion to integral symmetric functions. It can be proved that integral symmetric functions can be reduced to sums of functions, each of which is homogeneous by itself, and of the type

(5)
$$\sum a_1^{p_1} a_2^{p_2} \dots a_n^{p_n}$$
, with $p_1 \ge p_2 \ge \dots \ge p_n \ge 0$.

This latter type is called a monomial symmetric function. It is often denoted by the symbol (p_1p_2 p_n). The number $w=p_1+p_2+\dots+p_n$ is defined as the weight and the number p_1 as the order of the function. The simplest of the monomial symmetric functions are the elementary functions

$$\Sigma a_1, \Sigma a_1 a_2, \Sigma a_1 a_2 a_3, \dots$$

and the sums of the powers

$$\Sigma a_1^r = s_r = (r).$$

A complete symmetric function of weight w is defined as the sum of all the monomial symmetric functions of weight w. It is here denoted by t_w .* We have

(8)
$$t_w = \sum \sum a_1^{p_1} a_2^{p_2} \dots a_n^{p_n}.$$

For example,

(9)
$$t_4 = \sum a_1^4 + \sum a_1^3 a_2 + \sum a_1^2 a_2^2 + \sum a_1^2 a_2 a_3 + \sum a_1 a_2 a_3 a_4.$$

^{*}Other notations for t_w are $H(\alpha_1, \alpha_2, \ldots, \alpha_n)$ and nH_w or II_w . Wronski designates $H(\alpha_1, \alpha_2, \ldots, \alpha_n)$ as the "Alephfunktion" of $\alpha_1, \alpha_2, \ldots, \alpha_n$. C. Smith (Treatise on Algebra, p. 289, §250) uses nH_w , not to designate the function, but the number of terms contained in it. Burnside and Panton, Theory of Equations, 2nd Edition, p. 297, use II_w for t_w , and the last three authors refer to the function as "homogeneous products." See further "Encyklopaedie der Mathematischen Wissenschaften," Teil I, Band I, Heft 4, p. 465.

We shall farther denote the elementary functions by the b's, where b_r = a_r/a_0 , and then

(10)
$$\sum a_1 a_2 \dots a_r = (-1)^r b_r,$$

(11)
$$a_0x^n + a_1x^{n-1} + \dots + a_n = 0$$
, or $x^n + b_1x^{n-1} + \dots + b_n = 0$,

is the equation which has the a's for roots. Also

(12)
$$a_0^{\pi} \sum a_1^{p_1} a_2^{p_2} \dots a_n^{p_n} = \sum A_{\kappa} a_0^{\kappa_0} a_1^{\kappa_1} \dots a_n^{\kappa_n}$$
 (the expressibility proposition),

(13)
$$\kappa_1 + 2\kappa_2 + \dots + n\kappa_n = w$$
, (the weight proposition),

(14)
$$\kappa_0 + \kappa_1 + \dots + \kappa_n = \pi, \ \pi = p_1$$
, (the order proposition).

The t's are analogous to the b's (or elementary symmetric functions) in many of their properties,* while in other relations they play a rôle analogous to that of the s's.

The object of this paper is to state and solve some problems in symmetric functions, to sketch the theory of the t's, and to exhibit tables, which express up to weight five, homogeneous products of the t's in terms of homogeneous products of other symmetric functions, and vice versa, and to point out certain properties of such tables.

- 2. The Statement of Some Problems in Symmetric Functions.
- (i). On Expressibility. Fundamental Systems.

Besides the problem on expressibility whose solution is stated in (12), others have arisen. This leads to the concept of a fundamental system. A fundamental system for symmetric functions is any system of rational symmetric functions, by means of which any rational symmetric function can be rationally expressed.† Of such systems the following are known to exist:

(15)
$$b_1, b_2, \dots, b_n; \dagger s_1, s_2, \dots, s_n; \S$$

 $s_1, s_3, \dots, s_{2n-1}; \parallel s_v, s_{v_2}, \dots, s_{v_n}. \P$

In the last system the ν 's are the first n integers which are not multiples

$$(p_1p_2.....p_n) = \begin{vmatrix} u_{1\,1}u_{1\,2}......u_{1n} \\ \vdots & \vdots & \vdots \\ v_{n\,1}v_{n\,2}........v_{nn} \end{vmatrix}, \text{ where } u_{1\,1} = s_{p_1}, u_{2\,2} = s_{p_2}, u_{1\,2}u_{1\,1} = s_{p_1+p_2},$$

$$u_{12}u_{23}u_{31} = s_{p_1+p_2+p_3}$$
, etc.

 $u_{1\,2}\,u_{2\,3}u_{3\,1}\!=\!s_{p_1+p_2+p_3}\;,\;\;\text{etc.}$ This proves $s_1,\,s_2,\,\ldots,\,s_n$ a fundamental system. See Am. Math. Monthly, Vol. 5, p. 161.

^{*}This appears to have its basis in the relations expressed in (35) and (36) of this paper.

[†]See Ency. der Math. Wiss. loc. cit., p. 455.

[†]Contained in (12).

It can be proved that

^{||}Proved by Borchardt. Gesammelte Werke, p. 107.

Proved by Vahlen. Ueber Fundamentalsysteme fuer Symmetrische Functionen. Acta Mathematica. Band 23, p. 91.

of a given integer, and this system is the generalization of and contains the two preceding systems. It is evident from (33) of this paper that

$$(16) t_1, t_2, \dots, t_n; t_1, t_2, t_3, \dots, t_{2n-1}; t_1, t_2, t_3, \dots, t_{v_n};$$

are also fundamental systems, but it would be interesting to know if the last two would remain fundamental systems, if such of the t's were omitted as would make these systems analogues of the last two systems of (15). This question is left for future investigation.

(ii). Other Problems.

It is well known that the general equation (10) can not be solved algebraically when n>4, but in case the roots enter an expression symmetrically, it is not necessary to find them in order to find the value of the expression. Thus symmetric functions solve problems where all the roots enter symmetrically without the necessity of finding them:

a. To find the general term in the development of

(17)
$$\phi(x) = \frac{d_0 + d_1 x + \dots + d_m x^m}{a_0 + a_1 x + \dots + a_n x^n} = \frac{c_1 + 2c_2 x + 3c_3 a^2 + \dots + (m+1)c_{m+1} x^m}{1 + b_1 x + b_2 x^2 + \dots + b_n x^n}.$$

b. To find the value of

(18)
$$\sum_{\kappa=0}^{\kappa=\infty} \frac{\kappa r}{\kappa!}.$$

The solutions of these problems are given later (Part III).

PART II. THE THEORY OF THE t'S.

We have

(19)
$$x^n + b_1 x^{n-1} + b_2 x^{n-2} + \dots + b_n = (x - a_1)(x - a_2) \dots (x - a_n),$$

(20)
$$1 + b_1 x + b_2 x^2 + \dots + b_n x^n = (1 - a_1 x)(1 - a_2 x) \dots (1 - a_n x)$$
, whence

(21)
$$\frac{1}{1+b,x+b,x^2+\dots,b_nx^n} = t_0 + t_1x + t_2x^2 + \dots, * \text{ or }$$

(22)
$$1 = (t_0 + t_1 x + t_2 x^2 + \dots + b_n x^n).$$

In (22) the coefficient of $x^r=0$, if r>0, hence

$$(23) a_0 t_r + a_1 t_{r-1} + \dots + a_r t_0 = 0.$$

From the symmetry of (23) it follows that t_r is the same function of the a's that a_r is of the t's. Changing r into r-1, etc., in (23) we obtain r equations. Solving them for t_r , and noticing that $t_0=1$, we have,

^{*}See Burnside and Panton, l. c., p. 297.

(24)
$$a_0^r t_r = (-1)^r \begin{vmatrix} a_1 a_2 & \dots & a_r \\ a_0 a_1 & \dots & a_{r-1} \\ 0 & a_0 & \dots & a_{r-2} \\ \vdots & \vdots & \vdots \\ 0 & 0 & \dots & a_0 a_1 \end{vmatrix} = (-1)^r [1 \ 2 \dots r]_a.$$

Also by the preceding remark,

(25)
$$t_0^r a_r = (-1)^r [1 \ 2 \dots r]_t.$$

Writing (21) in the form $(1+\theta)^{-1}=t_0+t_1x+\dots$, where $\theta=b_1x+\dots+b_nx^n$, and developing by the binomial and multinomial theorems, and equating the coefficients of x^r ,

(26)
$$a_0^r t_r = \sum (-1)^{\kappa_1 + \kappa_2 + \dots + \kappa_r} \frac{(\kappa_1 + \kappa_2 + \dots + \kappa_r)!}{\kappa_1! \kappa_2! \dots \kappa_r!} a_0^{\kappa_0} a_1^{\kappa_1} \dots a_r^{\kappa_r}.$$
 Similarly,

(27)
$$t_0^r a_r = \sum (-1)^{\kappa_1 + \kappa_2 + \dots + \kappa_r} \frac{(\kappa_1 + \kappa_2 + \dots + \kappa_r)!}{\kappa_1 ! \kappa_2 ! \dots + \kappa_r !} t_0^{\kappa_0} t_1^{\kappa_1} \dots t_r^{\kappa_r},$$
$$\kappa_0 + \kappa_1 + \dots + \kappa_r = \kappa_1 + 2\kappa_2 + \dots + \kappa_r = r.$$

By equating (26) and (24), we get the development of the determinant in the right member of (24). If in (24) $a_0 = a_1 = \dots = a_r = 1$, 0 < r < n+1, the determinant vanishes, and

(28)
$$\Sigma \left(-1\right)^{\kappa_1+\kappa_2+\ldots+\kappa_n} \frac{\left(\kappa_1+\kappa_2+\ldots+\kappa_r\right)!}{\kappa_1! \kappa_2! \ldots \kappa_r!} = 0,$$

i. e., the sum of the coefficients in the development of t_r expressed in terms of the a's vanishes. From (20) we get

(29)
$$\log(1+b_1x+....+b_nx^n) = -\sum_{r=0}^{s_rx^r} = f_1(a)x+f_2(a)x^2+....+f_r(a)x^r+....$$

(30)
$$-\log(1+t_1x+....) = -\sum_{r=0}^{s_rx^r} = -f_1(t)x - f_2(t)x^2 + + f_r(t)x^r +,$$

whence

(31)
$$s_r = -rf_r(a) = (-1)^r \begin{vmatrix} b_1 & 1 & 0 & \dots & 0 \\ 2b_2 & b_1 & 1 & 0 & \dots & 0 \\ \vdots & \vdots & & \vdots & & \vdots \\ r & b_r & b_{r-1} & \dots & \dots & b_1 \end{vmatrix}$$

$$=r\mathbf{Z}(-1)^{\kappa_1+\cdots+\kappa_r}\frac{(\kappa_1+\ldots+\kappa_r-1)!}{\kappa_1!\kappa_2!\ldots\kappa_r!}b_1^{\kappa_1}b_2^{\kappa_2}\ldots b_r^{\kappa_r},*$$

^{*}Burnside and Panton, l. c., p. 298.

where with 0 < r < n+1, the sum of the coefficients of s_r (in terms of b's)=-1, and

(32)
$$\Sigma (-1)^{\kappa_1 + \dots + \kappa_r} \frac{(\kappa_1 + \dots + \kappa_r - 1)!}{\kappa_1 ! \dots \kappa_r!} = -\frac{1}{r}.$$
 Similarly,

(33)
$$s_{r} = (-1)^{r+1} \begin{vmatrix} t_{1} & 1 & 0 & \dots & \theta \\ 2t_{2} & t_{1} & 1 & 0 & \dots & \theta \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ r & t_{r} & t_{r-1} & \dots & \dots & t_{1} \end{vmatrix}$$

$$= -r \sum (-1)^{\kappa_{1} + \dots + \kappa_{r}} \frac{(\kappa_{1} + \dots + \kappa_{r} - 1)!}{\kappa_{1}! \dots \kappa_{r}!} t_{1}^{\kappa_{1}} \dots t_{r}^{\kappa_{r}}, \text{ with }$$

(34) the sum of the coefficients of s_r (in terms of the t's)=1. We may also write (29) and (30) in the forms

(35)
$$1 + b_1 x + \dots = e^{-\sum (s_r x^r/r)},$$

(36)
$$1+t_1x+...=e^{\sum (s_rx^r/r)}$$

and obtain,

(37)
$$b_r = \sum_{r=1}^{\infty} (-1)^{\frac{\kappa_1 + \dots + \kappa_r}{\kappa_1 + \dots + \kappa_r}} \left(\frac{s_1}{1}\right)^{\kappa_1} \left(\frac{s_2}{2}\right)^{\kappa_2} \dots \left(\frac{s_r}{r}\right)^{\kappa_r} *$$

(38)
$$t_r = \sum_{\kappa_1 \mid \dots \mid \kappa_r \mid} \frac{1}{(s_1)^{\kappa_1} \left(\frac{s_2}{2}\right)^{\kappa_2} \dots \left(\frac{s_r}{r}\right)^{\kappa_r}}$$

In fact (35) and (36) show that changing s into -s, converts b into t. This principle enables us to derive many new relations instantly from given relations. Thus (38) is derived in this way from (37), and the Newtonian identies

(39)
$$s_r + s_{r-1}b_1 + s_{r-2}b_2 + \dots + rb_r = 0, \dagger r = 1, 2, \dots$$

yield by this operation at once the analogous relations,

(40)
$$s_r + s_{r-1}t_1 + s_{r-2}t_2 + \dots + rt_r = 0. \ddagger$$

The principle also yield's this general theorem:

Any symmetric function expressed in terms of s's may be expressed in terms of t's, by changing s into -s, and then changing b into t, in each s expressed in terms of b's.

^{*}Burnside and Panton, l. c., p. 298.

[†]Burnside and Panton, l. c., p. 290.

[†]This relation has also been observed by L. Crocchi, "Una relazione fra a funzioni simmetriche semplici e le funzioni simmetriche complete." G. Battaglini's "Jiornale Mathematiche," etc., XVIII, 377-380.

The formulas (40) give also

(41)
$$t_r = \frac{(-1)^{r+1}}{r!} \begin{vmatrix} s_1 & 1 & 0 & 0 & \dots & 0 \\ s_2 & -s_1 & 2 & 0 & \dots & 0 \\ \vdots & & & & & \\ s_r & -s_{r-1} & \dots & \dots & -s_1 \end{vmatrix},$$

where the sum of the coefficients is 1, or by (38),

$$\sum_{\kappa_1} \frac{1}{|\dots \kappa_r|} \left(\frac{1}{1}\right)^{\kappa_1} \left(\frac{1}{2}\right)^{\kappa_2} \dots \left(\frac{1}{r}\right)^{\kappa_r} = 1.$$

And the formulas (39) give

(42)
$$b_r = \frac{(-1)^r}{r!} \begin{vmatrix} s_1 & 1 & 0 \dots & 0 \\ s_2 & s_1 & 2 & \dots & 0 \\ \dots & & r-1 \\ s_r & s_{r-1} & \dots & s_1 \end{vmatrix},$$

where by (37),

Some other relations satisfied by the t's are the following, which are stated without details of proof:

(44)
$$s_r = -(b_1 t_{r-1} + 2b_2 t_{r-2} + 3b_3 t_{r-3} + \dots + rb_r t_0).$$

This is obtained by expanding (31) in terms of the elements of the first column, and having regard to (24), or by differentiating (29) with respect to x, and using (21).

(45)
$$\frac{\partial s_r}{\partial b_r} = -rt_{r-\kappa}, \quad \frac{\partial s_r}{\partial t_r} = rb_{r-\kappa}.$$

The first one of these can be obtained by differentiating (31) partially with respect to b_{κ} , and observing (26); the second by the remark following (38).

(46)
$$\frac{\partial t_{2r+\kappa}}{\partial b_{-}} = -(t_r^2 + 2t_{2r} + 2t_1t_{2r-1} + \dots + 2t_{r-1}t_{r+1}),$$

(47)
$$\frac{\partial t_{2r+1+\kappa}}{\partial b_{\kappa}} = -(2t_{2r+1} + 2t_1t_{2r} + 2t_2t_{2r-1} + \dots + 2t_rt_{r+1}).$$

(46) and (47) come from differentiating (21) partially with respect to b_{κ} . In (46) and (47) we may interchange t and b.

(48)
$$r\kappa \frac{\partial b_{\kappa}}{\partial s_{r}} + \frac{\partial s_{\kappa}}{\partial t_{r}} = 0, \quad r\kappa \frac{\partial t_{\kappa}}{\partial s_{r}} + \frac{\partial s_{\kappa}}{\partial b_{r}} = 0.$$

The first formula in (48) comes from combining (45) with the relation $\frac{\partial b_{\kappa}}{\partial s_{r}} = -\frac{1}{r}b_{\kappa-r}; *$ the second by changing s into -s, and interchanging b and t.

If $-\delta = \frac{\partial}{\partial a} + \frac{\partial}{\partial a} + \dots + \frac{\delta}{\partial a}$,

$$(49) \qquad \partial t_{\kappa} = (n + \kappa - 1)t_{\kappa - 1}.\dagger$$

(49) can be easily proved by mathematical induction.

(50)
$$\frac{-(b_1+b_3x^2+b_5x^4+\dots)}{(1-a_1^2x^2)(1-a_2^2x^2)\dots(1-a_n^2x^2)} = t_1+t_3x^2+t_5x^5+\dots$$

(50) comes from using x and -x successively in (21).

(51)
$$H(a_1, a_2, \dots, a_n) = H_m(a_1, a_2, \dots, a_\kappa) + H_{m-1}(a_1, \dots, a_\kappa) + H(a_{\kappa+1}, \dots, a_n) + \dots + H(a_{\kappa+1}, \dots, a_n) + \dots + H(a_{\kappa+1}, \dots, a_n) + \dots$$

(53)
$$\Pi_r = \sum_{i=1}^{n} \frac{a_1 n + r - 1}{f'(a_1)}. \|$$

*Burnside and Panton, l. c., p. 304. From this comes the relation

$$\frac{\partial t_{\kappa}}{\partial s_r} = \frac{1}{r} t_{\kappa-r}.$$

*This relation was communicated to me by Professor Gordan.

†Ency. der Math. Wiss., l. c., p. 465.

§1. c., and for a proof of this theorem see Muir's Determinants, p. 170, §125.

||Burnside and Panton, l. c., p. 297. See also Ency. der Math. Wiss., l. c., p. 459.